2×12 A Digital Dual Output MicroDLynxTM: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current



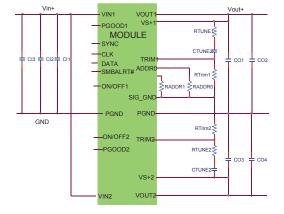




RoHS Compliant

Applications

- Distributed power architectures
- Intermediate bus voltage applications
- Telecommunications equipment
- Servers and storage applications
- Networking equipment
- Industrial equipment



Features

- Compliant to RoHS II EU "Directive 2011/65/EU"
- Compatible in a Pb-free or SnPb reflow environment
- Compliant to REACH Directive (EC) No 1907/2006
- Compliant to IPC-9592 (September 2008), Category 2, Class II
- Wide Input voltage range (4.5Vdc-14.4Vdc)
- Each Output voltage programmable from 0.6Vdc to 5.5Vdc via external resistor. Digitally adjustable down to 0.51Vdc
- Small size: 20.32 mm x 11.43 mm x 8.5 mm (0.8 in x 0.45 in x 0.335 in)
- Wide operating temperature range -40°C to 85°C
- Digital interface through the PMBus™ # protocol
- Tunable Loop™ to optimize dynamic output voltage response
- Power Good signal for each output
- Fixed switching frequency with capability of external synchronization
- 180° Out-of-phase to reduce input ripple
- Output overcurrent protection (non-latching)
- Output Overvoltage protection
- Over temperature protection
- Remote On/Off
- Ability to sink and source current
- Start up into Pre-biased output
- Cost efficient open frame design
- UL* 60950-1 2nd Ed. Recognized, CSA† C22.2 No. 60950-1-07 Certified, and VDE‡ (EN60950-1 2nd Ed.) Licensed
- ISO** 9001 and ISO 14001 certified manufacturing facilities

Description

The $2 \times 12A$ Digital Dual MicroDlynxTM power modules are non-isolated dc-dc converters that can deliver up to $2 \times 12A$ of output current. These modules operate over a wide range of input voltage ($V_{IN} = 4.5 \text{Vdc} - 14.4 \text{Vdc}$) and provide precisely regulated output voltages from 0.51Vdc to 5.5Vdc, programmable via an external resistor and PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, over current and over temperature protection. The PMBus interface supports a range of commands to both control and monitor the module. The module also includes the Tunable LoopTM feature that allows the user to optimize the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.

- * UL is a registered trademark of Underwriters Laboratories, Inc.
- † CSA is a registered trademark of Canadian Standards Association
- † VDE is a trademark of Verband Deutscher Elektrotechniker e.V.
- ** ISO is a registered trademark of the International Organization of Standards
- # The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)





2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage	All	V_{IN1} and V_{IN2}	-0.3	15	V
Continuous					
VS+1, VS+2, SMBALERT#	All		-0.3	7	V
CLK, DATA, SYNC,	All		-0.3	3.6	V
Operating Ambient Temperature	All	TA	-40	85	°C
(see Thermal Considerations section)					
Storage Temperature	All	T _{stg}	-55	125	°C

Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V _{IN1} and V _{IN2}	4.5	_	14.4	Vdc
Maximum Input Current	All	I _{IN1,max &} I _{IN2,max}			23	Adc
$(V_{IN}=4.5V \text{ to } 14.4V, I_0=I_{0, max})$						
Input No Load Current	V _{O,set} = 0.6 Vdc	I _{IN1,No} load & I _{IN2,No} load		72		mA
$(V_{IN} = 12Vdc, I_0 = 0, module enabled)$	V _{0,set} = 5.5Vdc	I _{IN,1No load} & I _{IN2,No load}		210		mA
Input Stand-by Current ($V_{IN} = 12Vdc$, module disabled)	All	I _{IN1,stand-by} & I _{IN2,stand-by}		14		mA
Inrush Transient	All	I ₁ ² t & I ₂ ² t			1	A ² s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1µH source impedance; V _{IN} =4.5 to 14V, I _O = I _{Omax} ; See Test Configurations)	All	Both Inputs		25		mAp-p
Input Ripple Rejection (120Hz)	All	Both Inputs		-68		dB



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 A Output Current

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Output Voltage Set-point (with 0.1% tolerance for external resistor used to set output voltage)	All	VO1, set & VO2, set	-1.0		+1.0	% VO, set
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	Vo1, set & VO2, set	-3.0	_	+3.0	% VO, set
Adjustment Range (selected by an external resistor) (Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section) *0.51V possible through PMBus command	All	VO1 & VO2	0.6*		5.5	Vdc
PMBus Adjustable Output Voltage Range	All	V ₀₁ ,adj, V ₀₂ ,adj	-15	0	+10	%V _{O,set}
PMBus Output Voltage Adjustment Step Size	All	Both outputs	0.4			%V _{O,set}
Remote Sense Range	All	Both outputs			0.5	Vdc
Output Regulation (for V ₀ ≥ 2.5Vdc)		Both Outputs				
Line ($V_{IN}=V_{IN, min}$ to $V_{IN, max}$)	All	Both Outputs		_	+0.4	% V _{O, set}
Load (I _O =I _{O, min} to I _{O, max})	All	Both Outputs		_	10	mV
Output Regulation (for $V_0 < 2.5 Vdc$)						
Line ($V_{IN}=V_{IN, min}$ to $V_{IN, max}$)	All	Both Outputs		_	5	mV
Load (I _O =I _{O, min} to I _{O, max})	All	Both Outputs		_	10	mV
Temperature ($T_{ref}=T_{A, min}$ to $T_{A, max}$)	All	Both Outputs		_	0.4	% V _{O, set}
Output Ripple and Noise on nominal output at 25°C						
(V_IN=V_IN, nom and Io=Io, min to Io, max Co = 2×0.1 + 2×47uF per output)						
Peak-to-Peak (5Hz to 20MHz bandwidth)	All		_	50	100	mV _{pk-pk}
RMS (5Hz to 20MHz bandwidth)	All			20	38	mV _{rms}
External Capacitance ¹						
Without the Tunable Loop™						
ESR≥1 mΩ	All	Co, max	2×47	_	2×47	μF
With the Tunable Loop™						
ESR ≥ 0.15 mΩ	All	Co, max		_	1000	μF
ESR ≥ 10 mΩ	All	Co, max		_	5000	μF
Output Current (in either sink or source mode)	All	l _o	0		12×2	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	I _{O, lim}		150		% I _{o,max}
Output Short-Circuit Current	All	l _{01, s/c} , l _{01, s/c}		6		Arms
(Vo≤250mV) (Hiccup Mode)						
Efficiency	V _{O,set} = 0.6Vdc	η 1, η 2		79		%
V _{IN} = 12Vdc, T _A =25°C	V _{O, set} = 1.2Vdc	η 1, η 2		88		%
I _O =I _{O, max} , V _O = V _{O,set}	V _{O,set} = 1.8Vdc	η 1, η 2		91		%
	V _{0,set} = 2.5Vdc	η 1, η 2		93		%
	V _{0, set} = 3.3Vdc	η 1, η 2		94		%
	$V_{0,set} = 5.0Vdc$	η 1, η 2		95		%
Switching Frequency	All	f _{sw}	_	500	_	kHz
internal canaditors may require using the new Tungble LeanTM for	1		المسام مم		the best tr	

¹ External capacitors may require using the new Tunable Loop[™] feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop[™] section for details.

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Frequency Synchronization	All					
Synchronization Frequency Range	All		-20%		+20%	kHz
High-Level Input Voltage	All	VIH	2.0			V
Low-Level Input Voltage	All	VIL			0.4	V
Input Current, SYNC	All	ISYNC			100	nA
Minimum Pulse Width, SYNC	All	tSYNC	100			ns
Maximum SYNC rise time	All	tSYNC_SH	100			ns

General Specifications

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (Io=0.8Io, max, T _A =40°C) Telecordia Issue 2 Method 1 Case 3	All		75,767,425		Hours
Weight		_	4.5 (0.16)	_	g (oz.)

Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface						
(V_IN=V_IN, $_{min}$ to V_IN, $_{max}$; open collector or equivalent,						
Signal referenced to GND)						
Device Code with no suffix – Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)						
Input High Current	All	lih1, lih2	_	_	1	mA
Input High Voltage	All	VIH1, VIH2	2	_	V _{IN, max}	Vdc
Logic Low (Module ON)						
Input low Current	All	lil1, lil2	_	_	20	μΑ
Input Low Voltage	All	VIL1, VIL2	-0.2	_	0.6	Vdc
Turn-On Delay and Rise Times						
(V _{IN} =V _{IN, nom} , I ₀ =I _{0, max} , V ₀ to within $\pm 1\%$ of steady state)						
Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN} = V_{IN,min}$ until $V_0 = 10\%$ of $V_0, set)$	All	Tdelay1, Tdelay2	_	2	_	msec
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until $V_0 = 10\%$ of V_0 , set)	All	Tdelay1, Tdelay2	-	800	-	µsec
Output voltage Rise time (time for V_0 to rise from 10% of V_0 , set to 90% of V_0 , set)	All	Trise1, Trise2	_	5	_	msec
Output voltage overshoot ($T_A = 25^{\circ}C$ $V_{IN} = V_{IN}$, m_{in} to V_{IN} , m_{ox} , $I_0 = I_0$, m_{in} to I_0 , m_{ox}) With or without maximum external capacitance		Both Outputs			3.0	% V _{O, set}

Specifications are subject to change without notice. It is responsibility of each customer to thoroughly test each product and part number under their unique parameters and environments to ensure a product will work properly and reliably





2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Feature Specifications (cont.)

Parameter	Device	Symbol	Min	Тур	Max	Units
Over Temperature Protection (See Thermal Considerations section)		Tref		135		°C
PMBus Over Temperature Warning Threshold*	All	T _{WARN}		125		°C
Input Undervoltage Lockout						
Turn-on Threshold	All	Both Inputs			4.5	Vdc
Turn-off Threshold	All	Both Inputs			4.25	Vdc
Hysteresis	All	Both Inputs	0.15	0.2		Vdc
PMBus Adjustable Input Under Voltage Lockout Thresholds	All	Both Inputs	4		14	Vdc
Resolution of Adjustable Input Under Voltage Threshold	All	Both Inputs			250	mV
PGOOD (Power Good)						
Signal Interface Open Drain, V _{supply} ≤ 5VDC						
Overvoltage threshold for PGOOD ON	All	Both Outputs		108.33		%V _{O, set}
Overvoltage threshold for PGOOD OFF	All	Both Outputs		112.5		%V _{O, set}
Undervoltage threshold for PGOOD ON	All	Both Outputs		91.67		%V _{O, set}
Undervoltage threshold for PGOOD OFF	All	Both Outputs		87.5		%V _{O, set}
Pulldown resistance of PGOOD pin	All	Both Outputs		40	70	Ω
Sink current capability into PGOOD pin	All	Both Outputs			5	mA

^{*} Over temperature Warning – Warning may not activate before alarm and unit may shutdown before warning



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

Digital Interface Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics	•					•
Input High Voltage (CLK, DATA)		VIH	2.1			V
Input Low Voltage (CLK, DATA)		VIL			0.8	V
Input high level current (CLK, DATA)		I _{IH}	-10		10	μΑ
Input low level current (CLK, DATA)		I _{IL}	-10		10	mA
Output Low Voltage (CLK, DATA, SMBALERT#)	I _{OUT} =2mA	Vol			0.4?	V
Output high level open drain leakage current (DATA, SMBALERT#)	V _{OUT} =3.6V	Іон	0		10	μΑ
Pin capacitance		Co		0	1	pF
PMBus Operating frequency range	Slave Mode	Fрмв	10		400	kHz
Data hold time	Receive Mode Transmit Mode	thd:dat	0 300			ns
Data setup time		tsu:dat	250			ns
Measurement System Characteristics						•
Output current measurement range		I _{RNG}	0		18	А
Output current measurement gain accuracy (at 25°C)		I _{ACC}			±1	А
V _{OUT} measurement range		V _{OUT(rng)}	0.5		5.8	V
V _{OUT} measurement accuracy			-2		2	%

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 A Output Current

Characteristic Curves

The following figures provide typical characteristics for the $2 \times 12A$ Digital Dual MicroDlynxTM at 0.6Vo and 25°C.

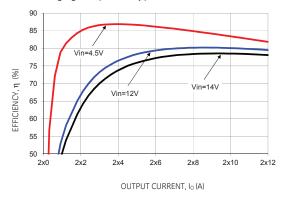


Figure 1. Converter Efficiency versus Output Current.

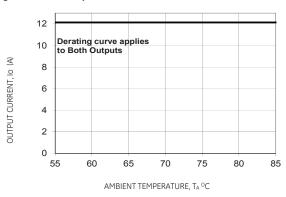
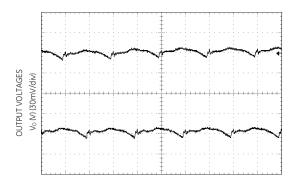
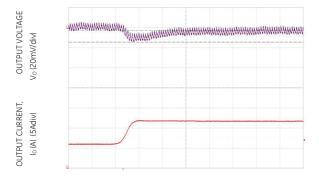


Figure 2. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (1µs/div)



TIME, t (20µs /div)

Figure 3. Typical output ripple and noise ($C_0=2\times0.1$ uF+ 2×47 uF ceramic, $V_{IN}=12V$, $I_0=I_{01,max}$, $I_{02,max}$, $I_{02,max}$).

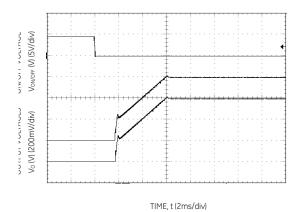
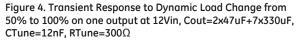
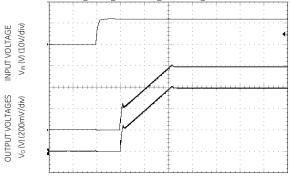


Figure 5. Typical Start-up Using On/Off Voltage (Vin=12V, Io = $lo_{1,max}$, $lo_{2,max}$,).





TIME, t (2ms/div)

Figure 6. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0.1 \text{ may } 10.2 \text{ may}}$)

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

Characteristic Curves

The following figures provide typical characteristics for the $2 \times 12A$ Digital Dual MicroDlynxTM at 1.2Vo and 25°C.

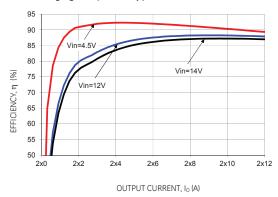


Figure 7. Converter Efficiency versus Output Current.

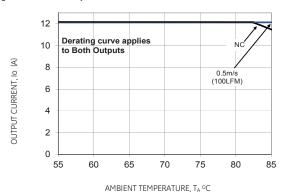


Figure 8. Derating Output Current versus Ambient Temperature and Airflow.

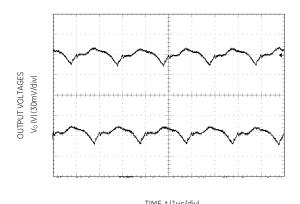


Figure 9. Typical output ripple and noise (C_0 = $2\times0.1uF+2\times47uF$ ceramic, V_{IN} = 12V, I_0 = $I_{01,max}$, $I_{02,max}$).

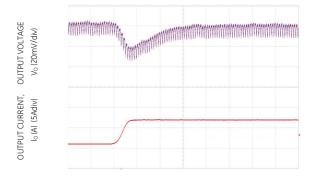


Figure 10. Transient Response to Dynamic Load Change on one output from 50% to 100% at 12Vin, Cout=3x47uF+3x330uF, CTune=2700pF & RTune=300 Ω

TIME, t (20µs /div)

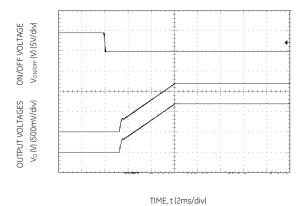


Figure 1. Typical Start-up Using On/Off Voltage ($V_{IN} = 12V$, $I_{O} = I_{O1,max}$, $I_{O2,max}$).

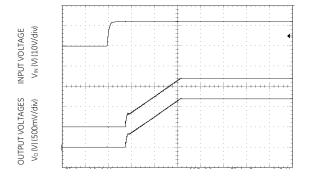


Figure 12. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{01,max}, I_{02,max}$).

TIME, t (2ms/div)

pecifications are subject to change without notice. It is responsibility of each customer to thoroughly test each product and part number under their unique parameters and environments to ensure a product will work properly and reliably

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 A Output Current

Characteristic Curves

The following figures provide typical characteristics for the $2 \times 12A$ Digital Dual MicroDlynxTM at 1.8Vo and 25°C.

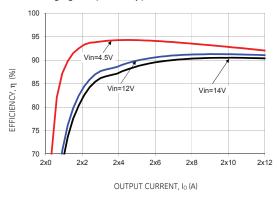


Figure 13. Converter Efficiency versus Output Current.

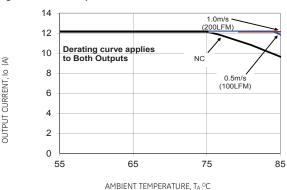
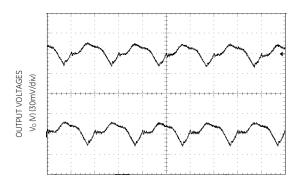
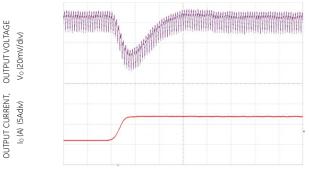


Figure 14. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (1µs/div)



TIME, t (20µs /div)

Figure 15. Typical output ripple and noise ($C_0=2\times0.1$ uF+2×47uF ceramic, $V_{IN}=12V$, $I_0=I_{01,max}$, $I_{02,max}$).

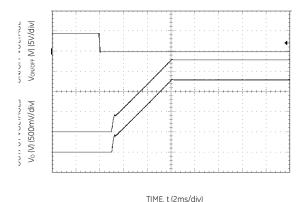
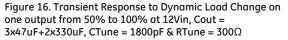
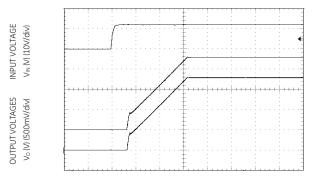


Figure 17. Typical Start-up Using On/Off Voltage ($V_{IN} = 12V$, $I_0 = I_{01,max}$, $I_{02,max}$).





TIME, t (2ms/div)

Figure 18. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{01,max}$, $I_{02,max}$).

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

Characteristic Curves

The following figures provide typical characteristics for the $2 \times 12A$ Digital Dual MicroDlynxTM at 2.5Vo and 25°C.

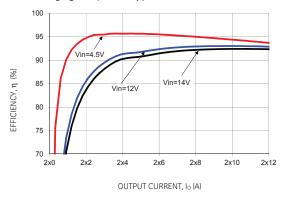


Figure 19. Converter Efficiency versus Output Current.

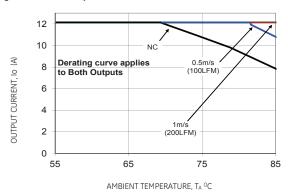


Figure 20. Derating Output Current versus Ambient Temperature and Airflow.

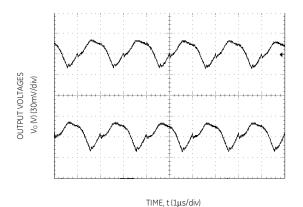
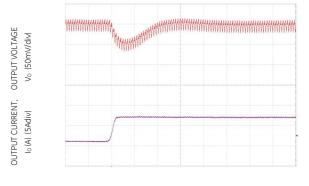


Figure 21. Typical output ripple and noise (Co= 2x0.1uF+2x47uF ceramic, Vin = 12V, Io = Io1,max, Io2,max).



TIME, t (20µs /div)

Figure 22. Transient Response to Dynamic Load Change on one output from 50% to 100% at 12Vin, Cout=3x47uF+2x330uF, CTune=1500pF & RTune = 300Ω

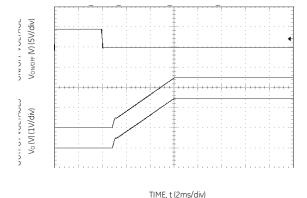
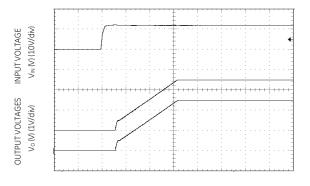


Figure 23. Typical Start-up Using On/Off Voltage ($V_{IN}=12V$, $I_0=I_{01,max}$, $I_{02,max}$).



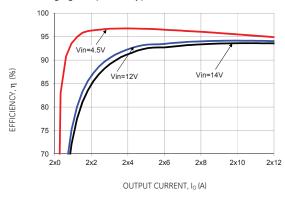
TIME, t (2ms/div)

Figure 24. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{01,max}$, $I_{02,max}$).

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Characteristic Curves

The following figures provide typical characteristics for the $2 \times 12A$ Digital Dual MicroDlynxTM at 3.3Vo and 25°C.



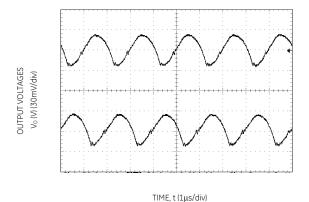
AMBIENT TEMPERATURE, TA °C

Figure 25. Converter Efficiency versus Output Current.

Figure 26. Derating Output Current versus Ambient Temperature and Airflow.

12

10



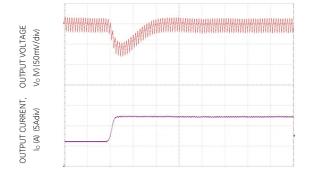
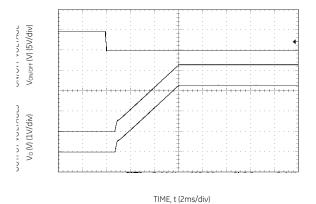


Figure 27. Typical output ripple and noise (Co= 2x0.1uF+2x47uF ceramic, Vin = 12V, Io = Io1,mox, Io2,mox).

Figure 28 Transient Response to Dynamic Load Change on one output from 50% to 100% at 12Vin, Cout=3x47uF+1x330uF, CTune = 1200pF & RTune = 300Ω

TIME, t (20µs /div)



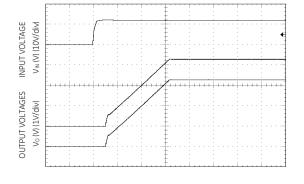


Figure 29. Typical Start-up Using On/Off Voltage ($V_{IN} = 12V$, $I_0 = I_{01,max}$, $I_{02,max}$).

Figure 30. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{01.max}$, $I_{02.max}$).

TIME, t (2ms/div)

pecifications are subject to change without notice. It is responsibility of each customer to thoroughly test each product and part number under their unique parameters and environments to ensure a product will work properly and reliably.

3.0m/s (600LFM)

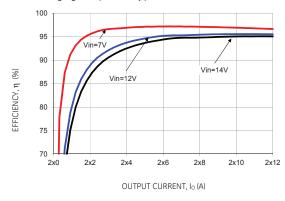
Measures: 0.80 x 0.45 x 0.335'

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

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Characteristic Curves

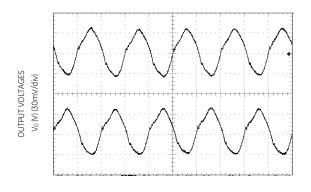
The following figures provide typical characteristics for the $2 \times 12A$ Digital Dual MicroDlynxTM at 5Vo and 25°C.



12 10 OUTPUT CURRENT, Io (A) 8 Derating curve applied to Both Outputs 6 (300LFM (200LFM) 0.5m/s (100LFM) 2 2m/s (400LFM) 0 85 45 55 65 AMBIENT TEMPERATURE, TA °C

Figure 31. Converter Efficiency versus Output Current.

Figure 32. Derating Output Current versus Ambient Temperature and Airflow.



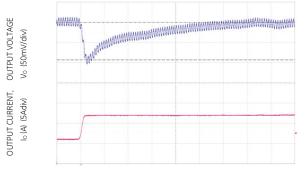
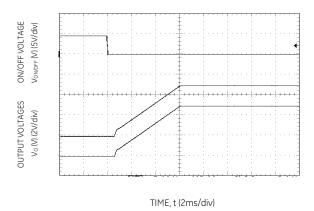


Figure 33. Typical output ripple and noise ($C_0 = 2 \times 0.1 uF + 2 \times 47 uF$ ceramic, $V_{IN} = 12 V$, $I_0 = I_{01,max}$, $I_{02,max}$).

TIME, t (1µs/div)

Figure 34. Transient Response to Dynamic Load Change on one output from 50% to 100% at 12Vin, Cout=6x47uF, CTune=470pF & RTune=300 Ω

TIME, t (20µs /div)



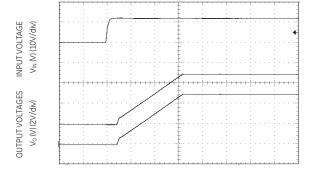


Figure 35. Typical Start-up Using On/Off Voltage ($V_{IN} = 12V$, $I_{o} = I_{o1,max}$, $I_{o2,max}$).

Figure 36. Typical Start-up Using Input Voltage ($V_{IN}=12V$, $I_0=I_{01,max},I_{02,max}$).

TIME, t (2ms/div)

ecifications are subject to change without notice. It is responsibility of each customer to thoroughly test each product and part number under their unique parameters and environments to ensure a product will work properly and reliably

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 A Output Current

Design Considerations

Input Filtering

The 2 \times 12A Digital Dual MicroDlynxTM module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 37 shows the input ripple voltage for various output voltages at2 x 12A of load current with 2x22 μF or 3x22 μF ceramic capacitors and an input of 12V.

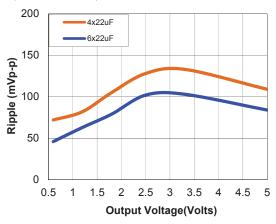


Figure 37. Input ripple voltage for various output voltages with 4x22 μ F or 6x22 μ F ceramic capacitors at the input (2 x 12A load). Input voltage is 12V.

Output Filtering

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with 0.1 μ F ceramic and 22 μ F ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 38 provides output ripple information for different external capacitance values at various Vo and a full load current of 2 x 12A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable Loop $^{\rm TM}$ feature described later in this data sheet.

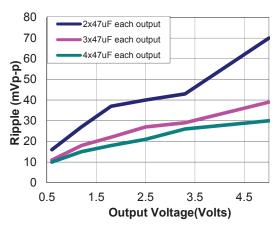


Figure 38. Output ripple voltage for various output voltages with total external 4x47 μ F, 6x47 μ F or 8x47 μ F ceramic capacitors at the output (2 x 12A load). Input voltage is 12V.

Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL 60950-1 2nd, CSA C22.2 No. 60950-1-07, DIN EN 60950-1:2006 + A11 (VDE0805 Teil 1 + A11):2009-11; EN 60950-1:2006 + A11:2009-03.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a fast-acting fuse with a maximum rating of 30A (voltage rating 125Vac) in the positive input lead. (Littelfuse 456 Series or equivalent)

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

Analog Feature Descriptions

Remote On/Off

The module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the two ON/OFF inputs:

- Module ON/OFF can be controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF can be controlled only through the PMBus interface (analog interface is janored)
- Module ON/OFF can be controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

Analog On/Off

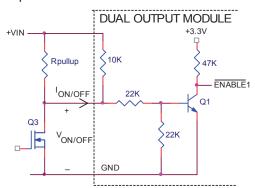
The 2 × 12A Digital Dual MicroDlynxTM power modules feature an On/Off pin for remote On/Off operation. Two On/Off logic options are available. In the Positive Logic On/Off option, (device code suffix "4" – see Ordering Information), the module turns ON during a logic High on the On/Off pin and turns OFF during a logic Low. With the Negative Logic On/Off option, (no device code suffix, see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. For either On/Off logic option, leaving the On/Off pin disconnected will turn the module ON when input voltage is present.

For positive logic modules, the circuit configuration for using the On/Off pin is shown in Figure 39. When the external transistor is in the OFF state, the internal transistor Q1 is turned ON, and the internal PWM Enable# signal(normally low) is pulled low causing the module to be ON. When ext. transistor is turned ON, the On/Off pin is pulled low, and the internal PWM Enable# signal(normally low) is pulled high and the module is OFF. For negative logic On/Off modules, the circuit configuration is shown in Fig. 40. When external transistor is in the OFF state, the On/Off pin is pulled high, transistor Q1 is turned ON and the internal PWM Enable signal is pulled low and the module is OFF. To turn the module ON, the external transistor is turned ON pulling the On/Off pin low, turning transistor Q1 OFF resulting in the PWM Enable pin going high and the module turns ON

Digital On/Off

Please see the Digital Feature Descriptions section.

Output 1



Output 2

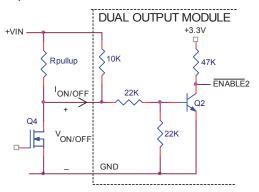
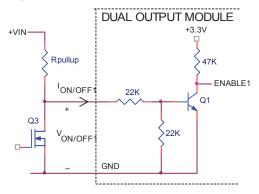


Figure 39. Circuit configuration for using positive On/Off logic.

Output 1



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Output 2

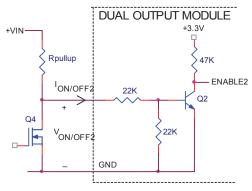


Figure 40. Circuit configuration for using negative On/Off logic.

Monotonic Start-up and Shutdown

The module has monotonic start-up and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

Startup into Pre-biased Output

The module can start into a prebiased output on either or both outputs as long as the prebias voltage is 0.5V less than the set output voltage.

Analog Output Voltage Programming

The output voltage of each output of the module shall be programmable to any voltage from 0.6dc to 5.5Vdc by connecting a resistor between the 2 Trims and SIG_GND pins of the module. Certain restrictions apply on the output voltage set point depending on the input voltage. These are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 1. The Upper Limit curve shows that for output voltages lower than 1V, the input voltage must be lower than the maximum of 14.4V. If the module can operate at 14.4V below 1V then that is preferable over the existing upper curve. The Lower Limit curve shows that for output voltages higher than 0.6V, the input voltage needs to be larger than the minimum of 4.5V.

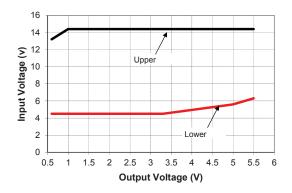
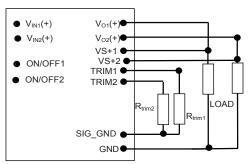


Figure 41. Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.



 ${\it Caution}$ – Do not connect SIG_GND to GND elsewhere in the layout

Figure 42. Circuit configuration for programming output voltage using an external resistor.

Without an external resistor between Trim and SIG_GND pins, each output of the module will be 0.6Vdc.To calculate the value of the trim resistor, *Rtrim* for a desired output voltage, should be as per the following equation:

$$Rtrim = \left[\frac{12}{(Vo - 0.6)} \right] k\Omega$$

Rtrim is the external resistor in $k\Omega$

Vo is the desired output voltage.

Table 1 provides Rtrim values required for some common output voltages.

Table 1

Vo, set (V)	Rtrim (KΩ)
0.6	Open
0.9	40
1.0	30
1.2	20
1.5	13.33
1.8	10
2.5	6.316
3.3	4.444
5.0	2.727

Digital Output Voltage Adjustment

Please see the Digital Feature Descriptions section.

Remote Sense

The power module has a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-) for each of the 2 outputs. The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.5V. If

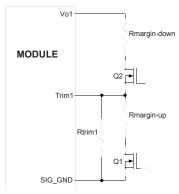
Specifications are subject to change without notice. It is responsibility of each customer to thoroughly test each product and part number under their unique parameters and environments to ensure a product will work properly and reliable

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

there is an inductor being used on the module output, then the tunable loop feature of the module should be used to ensure module stability with the proposed sense point location. If the simulation tools and loop feature of the module are not being used, then the remote sense should always be connected before the inductor. The sense trace should also be kept away from potentially noisy areas of the board

Analog Voltage Margining

Output voltage margining can be implemented in the module by connecting a resistor, R_{margin-up}, from the Trim pin to the ground pin for margining-up the output voltage and by connecting a resistor, R_{margin-down}, from the Trim pin to output pin for margining-down. Figure 43 shows the circuit configuration for output voltage margining. The POL Programming Tool, available at www.gecriticalpower.com in the Embedded Power group, also calculates the values of R_{margin-up} and R_{margin-down} for a specific output voltage and % margin. Please consult your local GE technical representative for additional details.



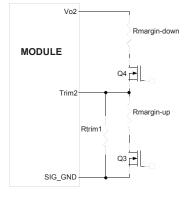


Figure 43. Circuit Configuration for margining Output voltage.

Digital Output Voltage Margining

Please see the Digital Feature Descriptions section.

Overcurrent Protection

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry on both outputs and can endure current limiting continuously. At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range.

Digital Adjustable Overcurrent Warning

Please see the Digital Feature Descriptions section.

Overtemperature Protection

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 135°C(typ) is exceeded at the thermal reference point T_{ref}. Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

Digital Temperature Status via PMBus

Please see the Digital Feature Descriptions section.

Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.

Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, the module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

Digitally Adjustable Input Undervoltage Lockout

Please see the Digital Feature Descriptions section.

Digitally Adjustable Power Good Thresholds

Please see the Digital Feature Descriptions section.

Synchronization

The module switching frequency can be synchronized to a signal with an external frequency within a specified range. Synchronization can be done by using the external signal applied to the SYNC pin of the module as shown in Fig. 45, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency. If synchronization is not being used, connect the SYNC pin to GND.

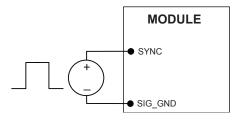


Figure 45. External source connections to synchronize switching frequency of the module.

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 A Output Current

Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

Tunable Loop™

The module has a feature that optimizes transient response of the module called Tunable Loop $^{\text{TM}}$.

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 38) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The Tunable $\mathsf{Loop}^\mathsf{TM}$ allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable $\mathsf{Loop}^\mathsf{TM}$ is implemented by connecting a series R-C between the VS+ and TRIM pins of the module, as shown in Fig. 47. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

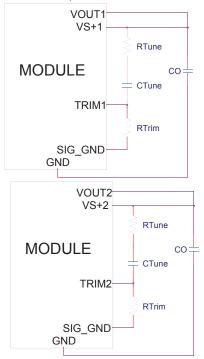


Figure. 47. Circuit diagram showing connection of R_{TUME} and C_{TUNE} to tune the control loop of the module.

Recommended values of R_{TUNE} and C_{TUNE} for different output capacitor combinations are given in Table 2. Table 2 shows the recommended values of R_{TUNE} and C_{TUNE} for different values of ceramic output capacitors up to 1000uF that might be needed for an application to meet output ripple and noise requirements. Selecting R_{TUNE} and C_{TUNE} according to Table 2 will ensure stable operation of the module. In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of R_{TUNE} and C_{TUNE} in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 6A to 12A step change (50% of full load), with an input voltage of 12V.

Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

Table 2. General recommended values of of R_{TUNE} and C_{TUNE} for Vin=12V and various external ceramic capacitor combinations.

Со	3x47μF	4x47μF	6x47μF	10x47μF	20x47μF
R _{TUNE}	300	300	300	300	300
C _{TUNE}	220pF	330pF	1000pF	1800pF	3900pF

Table 3. Recommended values of R_{TUNE} and C_{TUNE} to obtain transient deviation of 2% of Vout for a 6A step load with Vin=12V.

Vo	5V	3.3V	2.5V	1.8V	1.2V	0.6V
Co	6x47μF	330μF	3x47μF + 2x330μF Polymer	コンススハロ E	3x47μF + 3x330μF Polymer	2x47μF + 7x330μF Polymer
R _{TUNE}	300	300	300	300	300	300
C _{TUNE}	470pF	1200pF	1500pF	1800pF	2700pF	12nF
ΔV	84mV	39mV	30mV	27mV	20mV	10mV

Note: The capacitors used in the Tunable Loop tables are 47 μ F/2 m Ω ESR ceramic and 330 μ F/12 m Ω ESR polymer capacitors.

power@sager.com http://power.sager.com

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Digital Feature Descriptions

PMBus Interface Capability

The $2\times12A$ Digital Dual MicroDlynxTM power modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from www.pmbus.org. The modules support a subset of version 1.1 of the specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

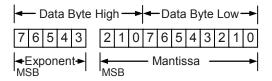
All communication over the module PMBus interface must support the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module

The module also supports the SMBALERT# response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

PMBus Data Format

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by

Value = Mantissa x 2 Exponent

PMBus Addressing

The power module can be addressed through the PMBus using a device address. The module has 64 possible addresses (0 to 63 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specifications and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (1% tolerance resistors are recommended). Note that if

either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

Table 4

Digit	Resistor Value (KΩ)
0	11
1	18.7
2	27.4
3	38.3
4	53.6
5	82.5
6	127
7	187

The user must know which I²C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, smbus.org.

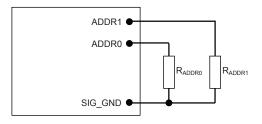


Figure 48. Circuit showing connection of resistors used to set the PMBus address of the module.

PAGE

Both the outputs of the module can be configured, controlled and monitored through only one physical address

Format		Unsigned Binary						
Bit Position	7	6	5	4	3	2	1	0
Access	r/w	r	r	r	r	r	r	r/w
Function	PA	Χ	Χ	Χ	Χ	Χ	Χ	P0
Default Value	0	Х	X	X	Х	Χ	Х	0

PAGE Command Truth Table

	PA	P0	Logic Results	
Г	0	0	All Commands address first output	
	0	1	All Commands address second output	
	1	0	Illegal input, Ignore write	
	1	1	All Commands address both outputs	

If PAGE=11, then any read commands affect the first channel. Any value to ready-only registers is ignored.

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 A Output Current

Operation (01h)

This is a paged register. The OPERATION command can be use to turn the module on or off in conjunction with the ON/OFF pin input. It is also used to margin up or margin down the output voltage

PMBus Enabled On/Off

The module can also be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON_OFF_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

0 : Output is disabled 1 : Output is enabled

This module uses the lower five bits of the ON_OFF_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	0

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	/alue Action	
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin	
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.	

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Value	Bit Value Action		
0	Module ignores the ON bit in the OPERATION command		
1	Module responds to the ON bit in the OPERATION command		

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

Bit Value	Action		
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the PMBUS via the OPERATION command		
1	Module requires the analog ON/OFF pin to be asserted to start the unit		

CPA: Sets the action of the analog ON/OFF pin when turning the controller OFF. This bit is internally read and cannot be modified by the user

PMBus Adjustable Soft Start Rise Time

The soft start rise time can be adjusted in the module via PMBus. When setting this parameter, make sure that the charging current for output capacitors can be delivered by the module in addition to any load current to avoid nuisance tripping of the overcurrent protection circuitry during startup. The TON_RISE command sets the rise time in ms, and allows choosing soft start times between 600µs and 9ms, with possible values listed in Table 5. Note that the exponent is fixed at -4 (decimal) and the upper two bits of the mantissa are also fixed at 0.

Table 5

Rise Time	Exponent	Mantissa
600µs	11100	0000001010
900µs	11100	0000001110
1.2ms	11100	00000010011
1.8ms	11100	00000011101
2.7ms	11100	00000101011
4.2ms	11100	00001000011
6.0ms	11100	00001100000
9.0ms	11100	00010010000

Output Voltage Adjustment Using the PMBus

The VREF_TRIM parameter is important for a number of PMBus commands related to output voltage trimming, and margining. Each of the 2 output voltages of the module shall be set as the combination of the voltage divider formed by RTrim and a $20k\Omega$ upper divider resistor inside the module, and the internal reference voltage of the module. The reference voltage V_{REF} shall be nominally set at 600mV, and the output regulation voltage is then given by

$$V_{OUT.1} = \left[\frac{20000 + RTrim1}{RTrim1}\right] \times V_{REF}$$

$$V_{OUT.2} = \left[\frac{20000 + RTrim2}{RTrim2}\right] \times V_{REF}$$

Hence the module output voltages shall be dependent on the value of RTrim1 and Rtrim2 which are connected external to the module.

The VREF_TRIM parameter is used to apply a fixed offset voltage to the reference voltage shall be specified using the "Linear" format and two bytes. The exponent is fixed at -9

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(decimal). The resolution of the adjustment is 7 bits, with a resulting step size of approximately 0.4%. The maximum trim range is -20% to +10% of the nominal reference voltage(600mV) in 2mV steps. Permissible values range from -120mV to +60mV

When PMBus commands are used to trim or margin the output voltage, the value of V_{REF} is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module shall be adjustable with a minimum step size of 0.4% over a +10% to -20% range from nominal using the VREF_TRIM command over the PMBus.

The VREF_TRIM command shall be used to apply a fixed offset voltage to either of the output voltage command value using the "Linear" mode with the exponent fixed at -9 (decimal). The value of the offset voltage shall be given by

$$V_{REF(offset)} = VREF _TRIM \times 2^{-9}$$

This offset voltage shall be added to the voltage set through the divider ratio and nominal V_{REF} to produce the trimmed output voltage. If a value outside of the +10%/-20% adjustment range is given with this command, the module shall set it's output voltage to the upper or lower limit value (as if VOUT_TRIM, assert SMBALRT#, set the CML bit in STATUS_BYTE and the invalid data bit in STATUS_CML.

Applications Example

For a design where the output voltage is 1.8V and the output needs to be trimmed down by 20mV.

- The internal reference voltage is 0.6V. So we need to determine how the 20mV translates to a change in the internal reference voltage.
- Divider Ratio = Vref/Vout = 0.6/1.8 = 0.33
- Hence a 20mV change at 1.8Vo requires a 0.33x20mV = 6.6mV change in the reference voltage.
- Vref(offset) = (6.6)/1000 = 0.0066 Volts (- sign since we are trimming down)
- V_{ref(offset)} = V_{ref_Trim} x 2 -9

low command

- $V_{ref_Trim} = V_{ref(offset)} x 512$
- $V_{ref_Trim} = -0.0066 \times 512 = -3.3 = -3$ (rounded to nearest integer

Output Voltage Margining Using the PMBus

Each output of the module shall also have its output voltage margined via PMBus commands. The command STEP_VREF_MARGIN_HIGH shall set the margin high voltage, while the command STEP_VREF_MARGIN_LOW sets the margin low voltage. Both the STEP_VREF_MARGIN_HIGH and STEP_VREF_MARGIN_LOW commands shall use the "Linear" mode with the exponent fixed at –9 (decimal). Two bytes shall be used for the mantissa with the upper bit [7] of the high byte shall be fixed at 0. The actual margined output voltage shall be a combination of the STEP_VREF_MARGIN_HIGH or STEP_VREF_MARGIN_LOW and the VREF_TRIM values as shown below. The net permissible voltage range change shall be -30% to +10% for the margin high command and -20% to 0% for the margin

 $V_{REF(MH)} =$

(STEP VREF MARGIN HIGH+VREF TRIM)×2⁻⁹

Applications Example

For a design where the output voltage is 1.2V and the output needs to be trimmed up by 100mV (within 10% of Vo).

- The internal reference voltage is 0.6V. So we need to determine how the 100mV translates to a change in the internal reference voltage.
- Divider Ratio = Vref/Vout = 0.6/1.2 = 0.5
- Hence a 100mV change at 1.2Vo requires a 0.5x100mV = 50mV change in the reference voltage.
- V_{REF(MH)} = (50)/1000 = 0.05 Volts
- V_{REF(MH)} = (Step_V_{ref_margin_high} + V_{ref_trim}) x 2 -9
- Assume V_{ref_Trim} = 0 here
- Step_V_{ref_margin_high} = V_{REF(MH)} x 512
- Step_V_{ref_margin_high} = 0.05 × 25.6 = 26 (rounded to nearest integer

 $V_{REF(ML)} =$

 $(STEP_VREF_MARGIN_LOW + VREF_TRIM) \times 2^{-9}$

Applications Example

For a design where the output voltage is 1.8V and the output needs to be trimmed down by 100mV (within -20% of Vo).

- The internal reference voltage is 0.6V. So we need to determine how the 100mV translates to a change in the internal reference voltage.
- Divider Ratio = Vref/Vout = 0.6/1.8 = 0.33
- Hence a 100mV change at 1.2Vo requires a 0.33x100mV = 33mV change in the reference voltage.
- V_{REF(MH)} = -(33)/1000 = -0.033 Volts (- sign since we are margining down)
- V_{REF(ML)} = (Step_V_{ref_margin_low} + V_{ref_trim}) x 2 -9
- Assume V_{ref_Trim} = 3 here (from V_{Ref_Trim} example earlier)
- Step_V_{ref_margin_low} = V_{REF(ML)} x 512 V_{ref_trim}
- Step_ $V_{ref_margin_low}$ = -0.033 × 512 (-3) = -16.9+3 = -13.9 = -14 (rounded to nearest integer

The module shall support the margined high or low voltages using the OPERATION command. Bits [5:2] shall be used to enable margining as follows:

00XX : Margin Off

 0101 : Margin Low (Act on Fault)

 0110 : Margin Low (Act on Fault)

 1001 : Margin High (Act on Fault)

 1010 : Margin High (Act on Fault)

PMBus Adjustable Overcurrent Warning

The module can provide an overcurrent warning via the PMBus. The threshold for the overcurrent warning can be set using the parameter IOUT_OC_WARN_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The exponent is fixed at -1 (decimal). The upper five bits of the mantissa are fixed at 0 while the lower

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six bits are programmable with a default value of 19A (decimal). The resolution of this warning limit is 500mA. The value of the IOUT_OC_WARN_LIMIT can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

Temperature Status via PMBus

The module will provide information related to temperature of the module through the READ_TEMPERATURE_2 command. The command returns external temperature in degrees Celsius. This command shall use the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte shall represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte shall represent the mantissa. The exponent is fixed at 0 (decimal). The lower 11 bits are the result of the ADC conversion of the external temperature

PMBus Adjustable Output Over, Under Voltage Protection and Power Good

The module has a common command to set the PGOOD, VOUT_UNDER_VOLTAGE(UV) and VOUT_OVER_VOLTAGE (OV) limits as a percentage of nominal. Refer to Table 6 of the next section for the available settings. The PMBus command VOUT_OVER_VOLTAGE (OV) shall be used to set the output over voltage threshold from two possible values: +12.5% or +16.67% of the commanded output voltage for each output.

The module provides a Power Good (PGOOD) for each output signal that shall be implemented with an open-drain output to indicate that the output voltage is within the regulation limits of the power module. The PGOOD signal shall be deasserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds. The PGOOD thresholds shall be user selectable via the PMBus (the default values are as shown in the Feature Specifications Section). Each threshold shall be set up symmetrically above and below the nominal value. The PGL (POWERGOODLOW) command shall set the output voltage level above which PGOOD is asserted (lower threshold). The PGH(POWERGOODHIGH) command shall set the level above which the PGOOD command is de-asserted. This command shall also set two thresholds symmetrically placed around the nominal output voltage. Normally, the PGL threshold shall be set higher than the PGH threshold.

The PGOOD terminal can be connected through a pullup resistor (suggested value $100 \mathrm{K}\Omega$) to a source of 5VDC or lower. The current through the PGood terminal should be limited to a max value of 5mA

PMBus Adjustable Input Undervoltage Lockout

The module allows for adjustment of the input under voltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold for each output, while the VIN_OFF command shall set the input voltage turn off threshold. For the VIN_ON command, possible values are 4.25V to 16V in variable steps. For the VIN_OFF command, possible values are 4V to 15.75V in 0.5V steps. If other values are entered for either command, they shall be mapped to the closest of the allowed values.

Both the VIN_ON and VIN_OFF commands use the "Linear" format with two data bytes. The upper five bits shall represent the exponent (fixed at -2) and the remaining 11 bits shall represent the mantissa. For the mantissa, the four most significant bits are fixed at 0.

Measurement of Output Current, Output Voltage and Input Voltage

The module is capable of measuring key module parameters such as output current and voltage for each outputs and input voltage for each input and providing this information through the PMBus interface.

Measuring Output Current Using the PMBus

The module measures current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then the current gain factor used to scale the measured voltage into a current reading. This gain factor is the argument of the IOUT_CAL_GAIN command, and consists of two bytes in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –15 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT_CAL_OFFSET command is used to store and read the current offset. The argument for this command consists of two bytes composed of a 5-bit exponent (fixed at -4d) and a 11-bit mantissa. This command has a resolution of 62.5mA and a range of -4000mA to +3937.5mA.

The READ_IOUT command provides module average output current information. This command only supports positive or current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ_IOUT command returns two bytes of data in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at – 4 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa with the 11th bit fixed at 0 since only positive numbers are considered valid.

Measuring Output Voltage Using the PMBus

The module provides output voltage information using the READ_VOUT command for each output. In this module the output voltage is sensed at the remote sense amplifier output pin so voltage drop to the load is not accounted for. The command shall return two bytes of data all representing the mantissa while the exponent is fixed at -9 (decimal).

Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. However, not all features are supported in these commands. A 1 in the bit position indicates the fault that is flagged.

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STATUS BYTE: Returns one byte of information with a summary of the most critical device faults.

Bit Position	Flag	
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3 VIN Undervoltage		0
2	Temperature	0
1 CML (Comm. Memory Fault) 0 None of the above		0
		0

STATUS_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

Low Byte

2011 2916				
Bit Flag		Default Value		
7	X	0		
6	OFF	0		
5	VOUT Overvoltage	0		
4	IOUT Overcurrent	0		
3	VIN Undervoltage	0		
2	Temperature	0		
1	CML (Comm. Memory Fault)	0		
0	None of the above			

High Byte

Bit Position	Floo	
7	VOUT fault or warning	0
6	IOUT fault or warning	0
5	X	0
4	MFR	0
3	POWER_GOOD# (is negated)	0
2	Χ	0
1	X	0
0	X	0

STATUS_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	X	0
5	X	0
4	VOUT UV Fault	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	X	0

5	IOUT OC Warning	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	X	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS CML: Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Command	0
5	Packet Error Check Failed	0
4	Memory Fault Detected	0
3	X	0
2	X	0
1	Other Communication Fault	0
0	X	0

MFR VIN MIN: Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12)

 ${\sf MFR_VOUT_MIN}: Returns\ minimum\ output\ voltage\ as\ two$ data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format - fixed at 614)

MFR_SPECIFIC_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (xxxxxx corresponds to the UDXS1212 series of module), while bits [7:3] indicate the revision number of the module.

Low Byte

	Bit Position	Flag	Default Value
ſ	7:2	Module Name	000011
	1:0	Reserved	10

High Byte



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Bit Position	Flag	Default Value
7:3	Module Revision Number	None
2:0	Reserved	000

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Summary of Supported PMBus Commands

Please refer to the PMBus 1.1 specification for more details of these commands.

Table 6

Hex	Command			Br	ief Desc	cription					Non-Volatile	
Code		Ability to configure					put by ι	using or	nly one i	physical	Memory Storage	
		address of the mo	dule									
		Format				Unsigne		_				
		Bit Position	7	6	5	4	3	2	1	0		
		Access Function	r/w PA	r X	r X	r X	r X	r X	r X	r/w P0		
		Default Value	0	X	X	X	X	X	X	0		
00	PAGE	PAGE Command T	uth Tak	ole								
		PA PO)		Lo	gic Resi	ults					
		0 0		All Co	mmand	ls addre	ss first	output				
		0 1		All Com	mands	addres	s secon	d outpu	ıt			
		1 0		II	legal in	put, Ign	ore wr	ite				
		1 1				addres			s			
		Turn Module on or	off. Also	o used to	o margii	n the ou	tput vo	ltage				
		Format				Unsigne	d Binar	У				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r	r/w	r/w	r/w	r/w	r	r		
		Function Default Value	On 0	X 0	0	0	rgin 0	0	X	X		
01	OPERATION		Default Value 0 0 0 0 0 X X Bit 7: 0 Output switching disabled									
			1 Output switching enabled									
		Margin: 00XX Marg		/ Act on	fault)							
		0101 Marg	,									
		1001 Marg	, ,									
		1010 Marg Configures the ON				o o mo bin	ation of	analaa	011/05	Taia		
		and PMBus comm		ictional	ity us u	COMBIN	טנוטוו טו	unulog	UN/UF	r þin		
		Format				Unsigne	d Binar	У				
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0	YES	
0.2	en_en_eeme	Access Function	r X	r X	r X	r/w pu	r/w cmd	r/w cpr	r/w pol	r cpa	1.20	
		Default Value	0	0	0	1	0	1	1	0		
		Refer to Page 19 fo	or detail	s on pu,	cmd, cp	or, pol a	nd cpa					
03	CLEAR_FAULTS	Clear any fault bits if the device has be				et, also r	eleases	the SM	1BALERT	T# signal		
		Used to control wr	iting to	the mod	lule via	PMBus.	Copies	the curr	ent rea	ister		
		setting in the mod	ule who	se comr	mand co	ode mat	ches th					
		into non-volatile m	emory	(EEPRON		e modul Unsigne						
		Bit Position	7	6	5	Unsigne 4	a Binar	2	1	0		
		Access	r/w	r/w	r/w	×	X	X	X	×		
		Function	bit7	bit6	bit5	Χ	Χ	Χ	Χ	Χ		
10	WRITE_PROTECT	Default Value	0	0	0	X bit6 or	X ni+7	Χ	Χ	X	YES	
10	WINIT_PROTECT	Bit5: 0 – Enables al 1 – Disables a						AGE OP	FRATI∩I	N	1 53	
		and ON_O						13L 01		•		
		Bit 6: 0 – Enables a	II writes	as perr	nitted ir	bit5 or	bit7					
		1 – Disables a OPERATIO							and			
		Bit7: 0 – Enables al										
		1 – Disables a	l writes	except :				T comm	nand			
		(bit5 and b	it6 mus	t be 0)								
		Stores all of the au	rront ct	orablo =	naictor	ottinas	in tha T	EDDON4	mome:	ay ac the		
15	STORE_USER_ALL	Stores all of the cu new defaults on po			egister s	seungs	ııı tüe E	EPKUM	memor	y us the		
		3.1. 22. 34.15 571 pt										
		•										



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Function Mantissa Default Value 0 0 0 1 0 0 Exponent -2 (dec), fixed Mantissa The upper four bits are fixed at 0 The lower seven are programmable with a default value of 9(dec). This corresponds to a default of 4.25V. Allowable values are • 4.25, in steps of 0.25V upto 9.5V. • 9.5V to 13V in increments of 0.5V • 13V to 16V in increments of 1V Sets the value of input voltage at which the module turns off Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 Access r r r r r r Function Exponent Mantissa Default Value 1 1 1 0 0 0	Hex Code	Command		Brief Description											
Total	16	RESTORE_USER_ALL	(EEPROM). The com												
Bit Position				s the h	ost syst	em/GUI	/CLI det	ermine	key cap	oabilitie	s of the				
Access			Format			Į	Jnsigne	d Binar	У						
Function				7	6	5	4	3	2	1	0				
Function PEC SPD ALRT Reserved Default Value 1 0 1 1 0 0 0 0	19	CAPABILITY						r			r				
PEC - 1 Supported SPD - 01 - max of 400kHz	1	G. II. 7.13.12.11 1		PEC			ALRT								
SPD -0.1 = max of 400kHZ				1	0	1	1	0	0	0	0				
Cannot be changed Bit Position 7 6 5 4 3 2 1			SPD -01 - max of 4		ported										
Bit Position						ar and E	xponen	t set to	-10. The	ese valu	ies				
NOUT_MODE			cannot be changed	d											
Function			Bit Position	7	6	5	4	3	2	1	0				
Function Mode Exponent	20	VOLIT MODE	Access	r	r	r	r	r	r	r	r				
Mode: Value fixed at 000, linear mode Exponent: Value fixed at 10111, Exponent for linear mode values is -9 Sets the value of input voltage at which the module turns on Format Bit Position 7 6 5 4 3 2 1 Access r r r r r r r r r Function Exponent Mantissa Default Value 1 1 1 1 0 0 0 0 Bit Position 7 6 5 4 3 2 1 Access r r/w r/w r/w r/w r/w r/w r/w r/w r/w r	20	VOO1_110DL							xponer						
Exponent: Value fixed at 10111, Exponent for linear mode values is -9 Sets the value of input voltage at which the module turns on Format Bit Position 7 6 5 4 3 2 1 Access r r r r r r r r r r Function Exponent Mantissa Default Value 1 1 1 1 0 0 0 0 Bit Position 7 6 5 4 3 2 1 Access r r r/w r/w r/w r/w r/w r/w r/w r/w r/w	1						1	0	1	1	1				
Sets the value of input voltage at which the module turns on Format Bit Position 7 6 5 4 3 2 1 Access r r r r r r r r r Function Exponent Mantissa Default Value 1 1 1 1 0 0 0 0 Bit Position 7 6 5 4 3 2 1 Access r r/w r/w r/w r/w r/w r/w r/w r/w r/w r				,							_				
Sets the value of input voltage at which the module turns off Format Linear, two's complement binary										is -9					
Bit Position 7 6 5 4 3 2 1 Access r r r r r r r Function Exponent Mantissa Default Value 1 1 1 1 0 0 0 Bit Position 7 6 5 4 3 2 1 Access r r/w Function Mantissa Default Value 0 0 0 1 0 0 0 Exponent -2 (dec), fixed Mantissa The upper four bits are fixed at 0 The lower seven are programmable with a default value of 9(dec). This corresponds to a default of 4.25V. Allowable values are • 4.25, in steps of 0.25V upto 9.5V. • 9.5V to 13V in increments of 0.5V • 13V to 16V in increments of 1V Sets the value of input voltage at which the module turns off Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 Access r r r r r r Function Exponent Mantissa Default Value 1 1 1 0 0 0				put volt											
Access	1								_	<i>-</i>					
Function Exponent Mantissa				7	6	_	4	3	2	1	0				
Default Value				r				r			r				
Bit Position 7 6 5 4 3 2 1						xponen									
Access r r/w r/w r/w r/w r/w r/w r/w r/w r/w r				<u> </u>		1					0				
Function											0				
Default Value 0 0 0 1 0 0 0 Exponent -2 (dec), fixed Mantissa The upper four bits are fixed at 0 The lower seven are programmable with a default value of 9(dec). This corresponds to a default of 4.25V. Allowable values are • 4.25, in steps of 0.25V upto 9.5V. • 9.5V to 13V in increments of 0.5V • 13V to 16V in increments of 1V Sets the value of input voltage at which the module turns off Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 Access r r r r r r r r r Function Exponent Mantissa Default Value 1 1 1 1 0 0 0 0				r	r/w	r/w			r/w	r/w	r/w				
Exponent -2 (dec), fixed Mantissa The upper four bits are fixed at 0 The lower seven are programmable with a default value of 9(dec). This corresponds to a default of 4.25V. Allowable values are • 4.25, in steps of 0.25V upto 9.5V. • 9.5V to 13V in increments of 0.5V • 13V to 16V in increments of 1V Sets the value of input voltage at which the module turns off Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 Access r r r r r r r r r Function Exponent Mantissa Default Value 1 1 1 1 0 0 0 0															
Mantissa The upper four bits are fixed at 0 The lower seven are programmable with a default value of 9(dec). This corresponds to a default of 4.25V. Allowable values are • 4.25, in steps of 0.25V upto 9.5V. • 9.5V to 13V in increments of 0.5V • 13V to 16V in increments of 1V Sets the value of input voltage at which the module turns off Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 Access r r r r r r r r r Function Exponent Mantissa Default Value 1 1 1 1 0 0 0 0	35	_		-	0	0	1	0	0	0	1	YES			
Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 Access r			The upper four bits The lower seven ar corresponds to a d 4.25, in 9.5V to												
Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 Access r			Sets the value of in	nut volt	age at v	which th	ie modi	ıle turn	s off						
Bit Position 7 6 5 4 3 2 1				- at voit						ry					
Access r r r r r r Function Exponent Mantissa				7							0				
Default Value 1 1 1 1 0 0 0			I 		-			 	+	-	r				
			Function			xponen	it			Mantiss	а				
Bit Position 7 6 5 4 3 2 1	1			1	1	1	1	0	0		0				
			Bit Position	7	6	5	4	3	2	1	0				
				r	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
Function Mantissa								tissa							
Default Value 0 0 0 1 0 0	1		1.		0	0	0	1	0	0	0				
Sepantal Value 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	36	VIN_OFF	Default Value 0 0 0 0 1 0 0 0 Exponent -2 (dec), fixed Mantissa The upper four bits are fixed at 0 The lower seven are programmable with a default value of 8(dec). This corresponds to a default of 4.0V. Allowable values are 4.00, in steps of 0.25V upto 9.75V. 10.25V to 11.75V in increments of 0.5V									YES			



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

Hex Code	Command		Brief Description turns the value of the gain correction term used to correct the measured											
		Returns the value o	f the go	iin corre	ection te	erm use	d to cor	rect the	e measu	ıred				
		Format			inear, tv	uo's cor	mnleme	nt hina	rv					
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r/w				
38	IOUT_CAL_GAIN	Function	<u>'</u>		xponer		'		Mantiss:		YES			
30	1001_CAL_GAIN	Default Value	1	0	0	0	1	0	0	V	11.5			
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function	1700	1700	17 00		tissa	17 00	17 00	17.00				
		Default Value		V· Vc	ariable b			v calibr	ation					
		Returns the value o	f the of							output				
		current				/		and Indiana						
		Format	-		inear, tv				•	0				
		Bit Position	7	6	5	4	3	2	1	0				
70	IOUT CAL OFFCET	Access	r	r	r	r	r	r/w	r Mantina	r	VEC			
39	IOUT_CAL_OFFSET	Function Default Value	1		xponen			+	Mantiss		YES			
			7	1	1 5	0	3	V 2	V 1	0				
		Bit Position Access		6		r/w				_				
		Function	r	r	r/w		r/w tissa	r/w	r/w	r/w				
		Default Value		\1.\1.	ariable b			y calib-	ation					
\vdash		Delault value	<u> </u>	v: VC	ariable b	พระน 01	ıı iuCl0l	y culibi	utiOH					
		Sets the output ove	rcurren		evel in A inear, tv				rv —					
		Bit Position	7	6	inear, tv	4	<u> </u>	2	1	0				
		Access	r	r	r	r	r	r	r	r				
		Function	<u>'</u>		xponer		'		Mantiss:					
46	IOUT_OC_FAULT_LIMIT	Default Value	1	1	1	1	1	0	0	0	YES			
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function	<u> </u>	., **	., **		tissa	., **	., ••	., ,,				
	Value maybe locked	Default Value	0	0	1	0	1	0	0	0				
	value maybe locked	Determines module undervoltage (UV) f		in resp	onse to	an IOU_	OC_FA	ULT_LIN	4IT or a	VOUT				
		Format				Jnsigne	d Dipar							
		Bit Position	7	6	5	Jusigne 4	a Biriar	2	1	0				
		Access	r	r	r/w	r/w	r/w	r	r	r				
		ACCESS			RS	RS	RS		<u> </u>					
, ,	IOLIT OC FALLET BECRONES	Function	Χ	Χ	[2]	[1]	[0]	Х	X	X	V/50			
47	IOUT_OC_FAULT_RESPONSE	Default Value	0	0	1	1	1	1	0	0	YES			
									. ~					
		RS[2:0] – Retry Setti 000 Unit do 111 Unit go Any other v	oes not oes thro	ugh noi	rmal sof	t start o	continue	ously						
44	IOUT OC WARN LIMIT	Sets the output ove Format Bit Position Access Function	rcurren 7 r	6 r	ng level inear, tv 5 r	vo's cor 4 r	mpleme 3 r	2 r	ry 1 r Mantiss	0 r				
4A	IOUT_OC_WARN_LIMIT	Default Value	1	1	1	1	1	0	0	0				
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w				
		Function					tissa							
	Value may be locked	Default Value	0	0	1	0	0	1	1	0				
	,													



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Hex Code	Command				Brie	f Desc	ript	ion						Non-Volatile Memory Storage
		Sets the overtempe	eratu	re fault	level in °	С								mer, ciorago
		Format					com	nplemer	nt binary	/				
		Bit Position	7	6	5	4	ļ	3	2	1	0			
		Access	r	r		r	-	r	r	r	r			
4F	OT_FAULT_LIMIT	Function		1 0	Expon		. 1	_		lantiss				YES
		Default Value Bit Position	7	6		4	-	3	2	0	0	-		
		Access	r/\				-	r/w	r/w	r/w	r/w	-		
		Function	.,,	170	1700			issa	17 **	1, 00	17.00			
	Value may be locked	Default Value	1	0	0	C		0	1	1	1			
	, , , , , , , , , , , , , , , , , , , ,	Catatha a sucatama				1:- 00								
		Sets the over tempor	erati	ire warr			com	nplemer	nt hinarı	,				
		Bit Position	7	6		4	_	3	2	1	0			
		Access	r	_		r	_	r	r	r	r			
51		Function			Expon	ent			M	lantiss	a			YES
31	OT_WARN_LIMIT	Default Value	0			C	$\overline{}$	0	0	0	0			153
		Bit Position	7			4	-	3	2		0			
		Access Function	r/\	v r/v	v r/w		_	r/w issa	r/w	r/w	r/w			
	Value may be locked	Default Value	0	1	1	1 1		1	1	0	1	-		
-	,	L		_ '		- 1			-					
		Sets the rise time o Supported Values -							Value o	f () inst	tructs i	ınit to		
		bring its output to p	orogi	ammed	l value a	s quicl	kly a	s possib	ole	. 5 11131				
		Format	Ĭ					nplemer		/				
		Bit Position	7	6	5	4	ļ	3	2	1	0			
61	TON_RISE	Access	r	r		r	-	r	r	r	r/w			YES
01		Function Default Value	1	1	Expon 1	ent C	· I	0	0	lantiss 0	a 1 0	_		. 20
		Bit Position	7			4	$\overline{}$	3	2	1	0	-		
		Access	r/\				-	r/w	r/w	r/w	r/w	-		
		Function						issa						
		Default Value	0	0	1	C)	1	0	1	1			
		Returns one byte o	finfo	rmatior	n with a s					cal mo	dule fo	ults		
		Format				$\overline{}$	_	d Binary						
		Bit Position Access	7 r	6 r		r	-	3 r	2 r	1r	0 r	_		
78	STATUS_BYTE	Access				1			'		None	2		
		Flag	X	OF	F VOU			VIN_U V	TEMP	CML	of the			
					_0/			·			Abov	е		
		Default Value	0		_	C		0	0	0	0			
		Returns two bytes	of inf	ormatic	n with a	summ	nary	of the n	nodule's	s fault/	/warnir	ng		
		conditions						Unsign	ed Ring	rv				
		Bit Position		7	6	5	5	4	3	. y	2	1		
1		Access		r	r	r		r	r		r	r	П	
		Elaa	T	VOUT	IOUT/F	,		MFR	PGOC)D				
79	CTATUS WORD	Flag			001	×				_	Х	Χ		
19	STATUS_WORD	Default Value		0	0	C		0	0	\perp	0	0		
		Bit Position	_	7	6	5		4	3	+	2	1	\perp	
		Access		r	r	r	-	r	r	+	r	r	1.	
		Flag		Χ	OFF	VOL	JT_	IOUT_C	VIN_U	IV -	EMP	CML	No	
		Flug		^	OFF	0'	V	C	VIIN_U	اا ا ۷د	ויור	CIYIL	al	
		Default Value		0	Х	C)	0	0	\dashv	0	0		
		Returns one byte o	f info										hd	
		faults			. ******** ****************************		.5 01	11101	J	acput '	· ortuge		·u	
		Format				Unsi	gne	d Binary						
7A	STATUS_VOUT	Bit Position		7	6	5		4	3 2	_	0	_		
		Access	1.10	r	r	r		r	r ı	_	r	4		
		Flag Default Value	VC	OUT_OV 0	X 0	X 0		T_UV 0	X X		X 0	-		
		Delault value	l	U	U	U		v	U I (, 0	IU			



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

Hex Code	Command		Brief Description												Non-Volatile Memory Storage
		Returns one byte of	of infor	matic	n with	n the sto	atus of	the r	modu	le's ou	ıtput cu	rrent	relate	ed	
		faults Format		_			Unsig		Binar						
7B	STATUS_IOUT	Bit Position Access		7 r		6 r		5 r		_	4 3 r r	2 r	-	0 r	
		Flag Default Value	IOU	T_OC 0	Fault	X 0	IOUT C	0 0	arnin'		X X 0 C	X 0		X 0	
		Returns one byte o	of infor	matic	n with	n the sto	itus of	the r	nodu	le's te	mperati	ure re	lated		
		faults Format	Ults Format Unsigned Binary												
7D	STATUS_TEMPERATURE	Bit Position		7		6	5			3 2	2 1	0			
		Access		r	_	r	r	_		r ı		r			
		Flag Default Value	01_	FAUL 0	.1 (OT_WAR	N X	_	_	X	X X	X 0			
		Returns one byte of	of infor		n with								rela	ted	
		faults	Format Unsigned Binary												
		Bit Position	7		6	5	4	, a Di	3	2	1	П	0		
7E	STATUS_CML	Access	r		r	r	r		r	r	r		r		
		Flag	Invo		Invali Data	-	Memo faul detect	t	Χ	Χ	Othe Com Faul	m	Χ		
		Default Value	0		0	0	0	leu	0	0	0	ı	0		
		Returns one byte of	of infor	matic	n with	n the sto	itus of	the r	modu	le spe	cific fau	lts or	warr	ning	
		Format					ned Bir								
		Bit Position	7	6	5	4	3	2	1		0				
00	CTATUS MED COECIEIS	Access	r	r	r	r	r	r	r		R	-			
80	STATUS_MFR_SPECIFIC	Flag	OTFI	X	Х	IVADDI		Х	X	TWC	PH_EN				
		Default Value OTFI - Internal Ter IVADDR - PMBUs o TWOPH_EN - Mod	ddres:	s is no	ot valid	d	Shutdo	0 own	0 thres	hold	0]			
		Returns the value	of the	outpu	ıt volto	age of th	ne mod	ule.	Ехро	nent i	s fixed c	ıt -9.			
		Format			Lin	ear, two	s com	plen	nent b	oinary					
		Bit Position Access	7 r	_	6 r	5 r	4 r	3 r	_	2 r	1 r	0 r			
65	DEAD LIGHT	Function	+ '		.	<u> </u>	Manti				<u> </u>	-			
8B	READ_VOUT	Default Value	0	_	0	0	0	0	_	0	0	0	1		
		Bit Position	7	_	6	5	4	3	_	2	1	0			
		Access Function	r		r	r	r Manti	r		r	r	r			
		Default Value	0		0	0	0	0		0	0	0	1		
-		Returns the value	of the	יימלוור	ıt Curr	ent of th	ne mod	ule							
		Format	or tile (υσιμά		ear, two			nent <u>k</u>	oinary			1		
		Bit Position	7	_	6	5	4	3		2	1	0			
		Access	r		r	r	r	R	\perp	r M	r	r			
8C	READ_IOUT	Function Default Value	1	Т	Exp 1	ponent 1	0	0	+	V M	ontissa V	V	1		
		Bit Position	7	-	6	5	4	3	_	2	1	0			
		Access	r		r	r	r	r		r	r	r			
		Function Default Value	V	-	v T	V	Manti V	ssa V	_	v	v	0			
		V - Variable	V		v	v	V	V		v	v	U	J		



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Table 6 (Continued)

Hex Code	Command		Brief Description											
Code		Returns the value a	of the ex	rternal t	emnera	ture in a	denree	Celsius				Memory Storage		
		Format	i the ex		inear, tu				rv		1			
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	R	r	r	r	ł			
		Function	'				IX		<u> </u>		ł			
8E	READ_TEMPERATURE_2	Default Value	0	0	Exponer 0	0	0	V	V	l v	ł			
OE	READ_TEMPERATURE_2	Bit Position	7	6	5	4	3	2	1	0	ł			
		Access	r	r	r	r	r	r	r	r				
		Function	'	'			<u> </u>	'	_ '	_ '	ł			
		Default Value	V	V	V	V	tissa V	V	V	0				
		V - Variable	V	V	V	V	V	V	V	U	ļ			
		v - variable												
		Returns one byte in	dicatin	a the m	odule is	compli	ant to P	MBus S	nec 11	(read o	nlv)			
		Format	laicatiii	g the m		Jnsigne			pcc. 1.1	(read of	iy,			
98	PMBUS_REVISION	Bit Position	7	6	5	4	3	2	1	0				
30	111003_112131011	Access	r	r	r	r	r	r	r	r	ł			
		Default Value	0	0	0	1	0	0	0	1	ł			
		Delault value	U		U					1 +	J			
		Returns module na	me info	rmation	า									
		Format			Į	Jnsigne	d Binar	y			1			
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r	r	r	r	r	r	r	r				
		Function					erved				İ			
D0	MFR_SPECIFIC_00	Default Value	0	0	0	0	0	0	0	0	İ	YES		
		Bit Position	7	6	5	4	3	2	1	0	İ			
		Access	r	r	r	r	r	r	r	r	İ			
		Function				Name				erved	İ			
		Default Value	0	0	0	0	1	1	1	0	İ			
		Applies a fixed offse	et to the			age Mo	ıx trim r	ange is	-20% to	2 +10%	in 2mV			
		steps. Permissible v												
		as VREF_TRIMx2-9. (
		Format			_inear, tv		mpleme	ent bina	rv		I			
		Bit Position	7	6	5	4	3	2	1	0				
		Access	r/w	r	r	r	r	r	r	r	İ			
D4	VREF_TRIM	Function	.,		1		tissa				İ	YES		
		Default Value	V	V	V	V	V	V	V	V	İ			
		Bit Position	7	6	5	4	3	2	1	0	İ			
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w	İ			
		Function	<u> </u>		17 00		tissa	17 00	17 00	1700	ł			
		Default Value	V	V	V	V	V	V	V	V	ł			
		Applies a fixed offse					v	<u> </u>			/ ctonc			
		Permissible values									v steps.			
		(STEP_VREF_MARGI									nut			
		voltage includes VF								ivet out	.put			
		Format	(21_11(1)		inear, tu						1			
		Bit Position	7	6	5	4	3	2	1	0				
D5	CTED VIDEE MARCINI LIICU	Access	r	r	r	r	r	r	r	r	1	YES		
כט	STEP_VREF_MARGIN_HIGH	Function	- ' -	<u> </u>	<u> </u>		tissa	<u>' '</u>	<u> </u>	<u> </u>	1	YES		
		Default Value	V	V	V	V	V	V	V	V				
		Bit Position	7	6	5	4	3	2	1	0	1			
			<u> </u>	_						_				
1		Access	r	r	r	r/w	r/w	r/w	r/w	r/w	-			
		Function			T 1/		tissa			1.7				
		Default Value	V	V	V	V	V	V	V	V				



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

Table 6 (Continued)

Hex Code	Command					Brief I	Descri	ption						Non-Volatile Memory Storage	
		steps. Permissil (STEP_VREF_MA voltage include	Applies a fixed negative offset to the reference voltage. Adjustment is -20% to 0% in 2 teps. Permissible values range between -120mV and 0mV). The offset is calculated as STEP_VREF_MARGIN_LOW + VREF_TRIM)x2-9.Exponent fixed at -9(dec). Net output voltage includes VREF_TRIM adjustment and ranges from -30% to 10% Format Linear, two's complement binary												
		Bit Position	1	7	6	5	4	3	_	2	1	0			
D6	STEP VREF MARGIN LOW	Access		r	r	r	r	r	-	r	r	r	-	YES	
00	STEL _VIVEL _INANOIN_EOVV	Function					М	antissa				1		1123	
		Default Valu	ıe	V	V	V	V	V		V	V	V			
		Bit Position	ı	7	6	5	4	3		2	1	0			
		Access		r	r	r/w	r/w	/ r/\	N	r/w	r/w	r/w			
		Function					М	antissa							
		Default Valu	ıe	V	V	V	V	V	'	V	V	V			
		Single commar VOUT_OVER_V					ntage (of nom	inal						
		Format						Jnsigne							
		Bit Positio	n	7		6	5	4	3	3	2	1	0		
		Access		r		r	r	r	r	.	r	r/w	r/w		
		Function		X		X	Х	X	×	ζ	Х	PCT_ MSB	PCT_ LSB		
D7	PCT_VOUT_FAULT_PG_LIMIT	Default Val	ue	0		Х	Х	Χ	×	(Χ	Χ	0		
D1	FCI_VOOI_I AOLI_FG_LIMII	PAGE Comman	PAGE Command Truth Table												
		PCT_M PC SB	T_LS B	UV (9	%)	PGL LOW (%)	Н	GL IGH %)	PG HIG (%	iH	PGH LOW (%)		′ (%)		
		0	0	-16.6	57	-12.5	-8	3.33	12.	.5	8.33	16	5.67		
		0	1	-12.	5	-8.33	-4	.17	8.3	3	4.17	1	2.5		
		1	0	-29.1	L7	-20.83	-1	6.67	8.3	3	4.17	1	2.5		
		1	1	-41.6	57	-37.5	-3	3.33	8.3	3	4.17	1	2.5		
		Used to set dele from 0 to 7 and Format	ay to tu I are a r	rn-on o	or tur e of T	n-off mo	TIME			f TON_	_RISE. V	'alues co	an range		
D8	SEQUENCE_TON_TOFF_DELAY	Bit Position	1	7	6	5	4	Insigned Bir 4 3		2	1	0			
	SEQUENCE_TON_TOTT_DELAT	Access		r/w	r/w	r/w	r	r/\		r/w	r/w	r	1		
		Function			N_DE	LAY	TOFF DELAY					1			
		Default Valu	ıe	0	0	0	0	С		0	0	0			

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Thermal Considerations

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 49. The preferred airflow direction for the module is in Figure 50.

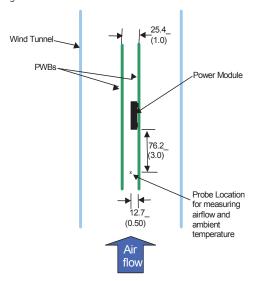


Figure 49. Thermal Test Setup.

The thermal reference points, T_{ref} used in the specifications are also shown in Figure 50. For reliable operation the temperatures at these points should not exceed 135°C. The output power of the module should not exceed the rated power of the module (Vo,set x lo,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

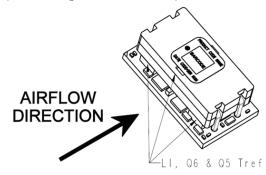


Figure 50. Preferred airflow direction and location of hotspot of the module (Tref).



2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12AOutput Current

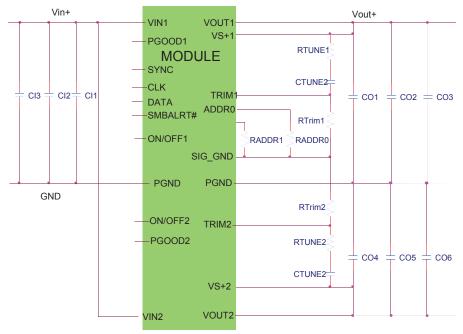
Example Application Circuit

Requirements:

Vin: 12V Vout: 1.8V

lout: $2 \times 9A$ max., worst case load transient is from 6A to 9A Δ Vout: 1.5% of Vout (27mV) for worst case load transient

Vin, ripple 1.5% of Vin (180mV, p-p)



CI1	Decoupling cap - 4x0.1μF/16V, 0402 size ceramic capacitor
CI2	4x22μF/16V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)
CI3	470μF/16V bulk electrolytic
CO1	Decoupling cap - 2x0.1μF/16V, 0402 size ceramic capacitor
CO2	$3 \times 47 \mu\text{F/6.3V}$ ceramic capacitor (e.g. Murata GRM31CR60J476ME19)
CO3	$1 \times 330 \mu F/6.3 \text{V}$ Polymer (e.g. Sanyo Poscap)
CO4	Decoupling cap - 2x0.1μF/16V, 0402 size ceramic capacitor
CO5	$3 \times 47 \mu\text{F/6.3V}$ ceramic capacitor (e.g. Murata GRM31CR60J476ME19)
CO6	$1 \times 330 \mu F/6.3 V$ Polymer (e.g. Sanyo Poscap)
CTune1	1200pF ceramic capacitor (can be 1206, 0805 or 0603 size)
RTune1	300 ohms SMT resistor (can be 1206, 0805 or 0603 size)
RTrim1	$10 k\Omega$ SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)
CTune2	1200pF ceramic capacitor (can be 1206, 0805 or 0603 size)
RTune2	300 ohms SMT resistor (can be 1206, 0805 or 0603 size)
RTrim2	$10 k\Omega$ SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

Note: The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the SMBus master controller will have the pull-up resistors as well as provide the driving source for these signals.

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules

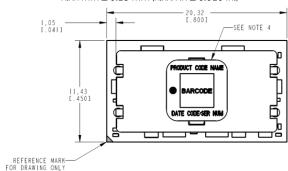
4.5Vdc -14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

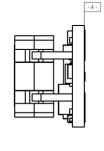
Mechanical Outline

Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated]

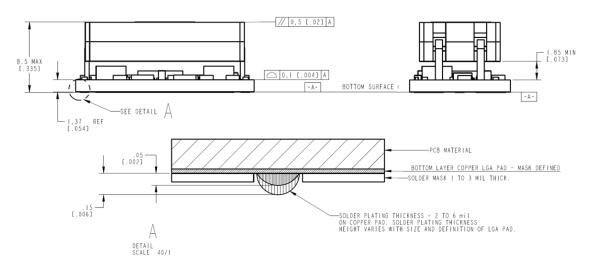
 $x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)$

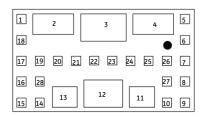




TOP VIEW

END VIEW





BOTTOM VIEW

PIN	FUNCTION	PIN	FUNCTION
1	VSNS1	15	ADDR1
2	VOUT1	16	TRIM1
3	PGND	17	Sig_GND
4	VOUT2	18	TRIM2
5	VSNS2	19	SYNC
6	SMBALERT#	20	PGND
7	DATA	21	PGND
8	CLK	22	PGND
9	ENABLE1	23	PGND
10	ENABLE2	24	PGND
11	VIN	25	PGND
12	PGND	26	PGND
13	VIN	27	PGOOD2
14	ADDRO	28	PGOOD1

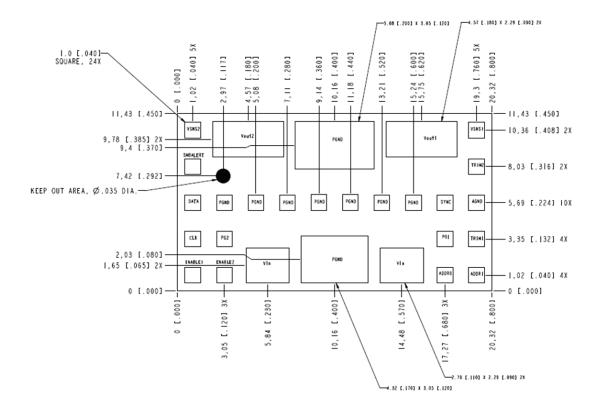
Specifications are subject to change without notice. It is responsibility of each customer to thoroughly test each product and part number under their unique parameters and environments to ensure a product will work properly and reliably.

2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12AOutput Current

Recommended Pad Layout

Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated] x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)



PIN	FUNCTION	PIN	FUNCTION		
1	VSNS1	15	ADDR1		
2	VOUT1	16	TRIM1		
3	PGND	17	Sig_GND		
4	VOUT2	18	TRIM2		
5	VSNS2	SNS2 19 SYN			
6	SMBALERT#	20	PGND		
7	DATA	21	PGND		
8	CLK	22	PGND		
9	ENABLE1	23	PGND		
10	ENABLE2	24	PGND		
11	VIN	25	PGND		
12	PGND	26	PGND		
13	VIN	27	PGOOD2		
14	ADDRO	28	PGOOD1		

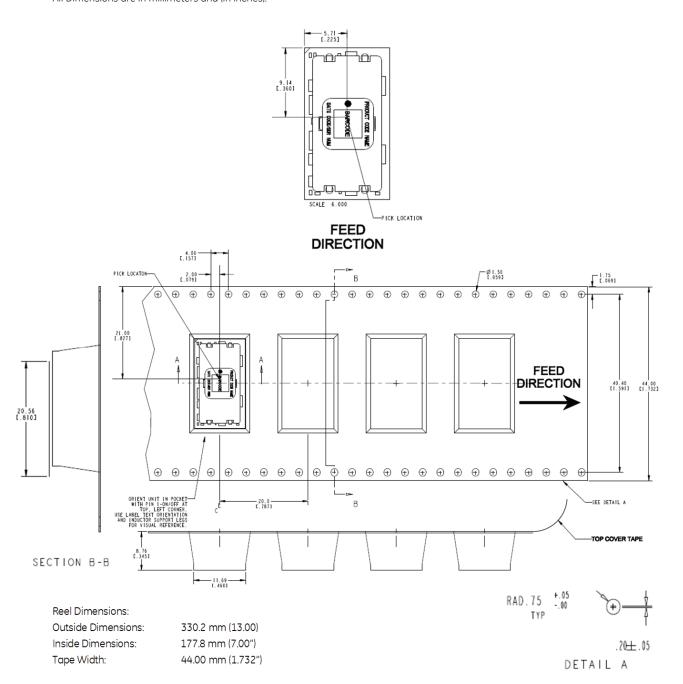
2 × 12A Digital Dual MicroDlynx™: Non-Isolated DC-DC Power Modules

4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Packaging Details

The 12V Digital Dual MicroDlynx TM 2 × 12A modules are supplied in tape & reel as standard. Modules are shipped in quantities of 200 modules per reel.

All Dimensions are in millimeters and (in inches).



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2×12 AOutput Current

Surface Mount Information

Pick and Place

The 2 \times 12A Digital Dual MicroDlynxTM modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

Nozzle Recommendations

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 3mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 7 mm.

Bottom Side / First Side Assembly

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

Lead Free Soldering

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

Pb-free Reflow Profile

Power Systems will comply with J-STD-020 Rev. D (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 50. Soldering outside of the recommended profile requires testing to verify results and performance.

MSL Rating

The 2 \times 12A Digital Dual MicroDlynxTM modules have a MSL rating of 3

Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed

packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of $\leq 30^{\circ}\text{C}$ and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: $< 40^{\circ}\,\text{C}, < 90\%$ relative humidity.

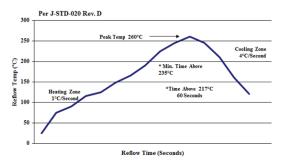


Figure 51. Recommended linear reflow profile using Sn/Ag/Cu solder.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to Board Mounted Power Modules: Soldering and Cleaning Application Note (AN04-001).

Specifications are subject to change without notice. It is responsibility of each customer to thoroughly test each product and part number under their unique parameters and environments to ensure a product will work properly and reliably



2×12 A Digital Dual MicroDlynxTM: Non-Isolated DC-DC Power Modules 4.5Vdc –14.4Vdc input; 0.51Vdc to 5.5Vdc output; 2 × 12A Output Current

Ordering Information

Please contact your GE Sales Representative for pricing, availability and optional features.

Table 9. Device Codes

Device Code	Input Voltage Range	Output Output Voltage Current		On/Off Logic	Sequencing	Comcodes
UDXS1212A0X3-SRZ	4.5 – 14.4Vdc	0.51 – 5.5 Vdc	12Ax2	Negative	No	150026732
UDXS1212A0X43-SRZ	4.5 – 14.4Vdc	0.51 – 5.5 Vdc	12Ax2	Positive	No	150033761

Table 10. Coding Scheme

Package Identifier	Family	Sequencing Option	Input Voltage	Output current	Output voltage	On/Off logic	Remote Sense	Options	ROHS Compliance
U	D	Х	S	1212A0	Х		3	-SR	Z
P=Pico U=Micro M=Mega G=Giga	D=Dlynx Digital V = DLynx Analog.	T=with EZ Sequence X=without sequencing	Special: 4.5 – 14V	2 × 12A	able output	4 = positive No entry = negative	3 = Remote Sense	S = Surface Mount R = Tape & Reel	Z = ROHS6

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